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# Estimation of the drift of fractional Brownian motion 

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#### Abstract

We consider the problem of efficient estimation for the drift of fractional Brownian motion $B^{H}:=\left(B_{t}^{H}\right)_{t \in[0, T]}$ with hurst parameter $H$ less than $\frac{1}{2}$. We also construct superefficient James-Stein type estimators which dominate, under the usual quadratic risk, the natural maximum likelihood estimator.


Key words : Fractional Brownian Motion, Stein estimate, MLE
2000 Mathematics Subject Classification: 60G15, 62G05, 62B05, 62M09.

## 1 Introduction

Fix $H \in(0,1)$ and $T>0$. Let $B^{H}=\left\{\left(B_{t}^{H, 1}, \ldots, B_{t}^{H, d}\right) ; t \in[0, T]\right\}$ be a $d$-dimensional fractional Brownian motion ( fBm ) defined on the probability space $(\Omega, \mathcal{F}, P)$. That is, $B^{H}$ is a zero mean Gaussian vector whose components are independent onedimensional fractional Brownian motions with Hurst parameter $H \in(0,1)$, i.e., for every $i=1, \ldots, d B^{H, i}$ is a Gaussian process and covariance function given by

$$
E\left(B_{s}^{H, i} B_{t}^{H, i}\right)=\frac{1}{2}\left(s^{2 H}+t^{2 H}-|t-s|^{2 H}\right), \quad s, t \in[0, T]
$$

For each $i=1, \ldots, d,\left(\mathcal{F}_{t}^{i}\right)_{t \in[0, T]}$ denotes the filtration generated by $\left(B_{t}^{H, i}\right)_{t \in[0, T]}$. The fBm was first introduced by [5] and studied by [6]. Notice that if $H=\frac{1}{2}$, the
process $B^{\frac{1}{2}}$ is a standard Brownian motion. However, for $H \neq \frac{1}{2}$, the fBm is neither a Markov process, nor a semi-martingale.

Let $M$ be a subspace of the Cameron-Martin space defined by

$$
\begin{aligned}
M=\{\varphi:[0, T] & \rightarrow \mathbb{R}^{d} ; \varphi_{t}^{i}=\int_{0}^{t} \dot{\varphi}_{s}^{i} d s \text { with } \dot{\varphi}^{i} \in L^{2}([0, T]) \\
& \text { and } \left.\varphi^{i} \in I_{0^{+}}^{H+\frac{1}{2}}\left(L^{2}([0, T])\right), i=1, \ldots, d\right\} .
\end{aligned}
$$

Let $\theta=\left\{\left(\theta_{t}^{1}, \ldots, \theta_{t}^{d}\right) ; t \in[0, T]\right\}$ be a function belonging to $M$. Then, Applying Girsanov theorem (see Theorem 2 in [9]), there exist a probability measure absolutely continuous with respect to $P$ under which the process $\widetilde{B}^{H}$ defined by

$$
\begin{equation*}
\widetilde{B}_{t}^{H}=B_{t}^{H}-\theta_{t}, \quad t \in[0, T] \tag{1.1}
\end{equation*}
$$

is a fBm with Hurst parameter $H$ and mean zero. In this case, we say that, under the probability $P_{\theta}$, the process $B^{H}$ is a fBm with drift $\theta$.

We consider in this paper the problem of estimating the drift $\theta$ of $B^{H}$ under the probability $P_{\theta}$, with hurst parameter $H<1 / 2$. We wish to estimate $\theta$ under the usual quadratic risk, that is defined for any estimator $\delta$ of $\theta$ by

$$
\mathcal{R}(\theta, \delta)=E_{\theta}\left[\int_{0}^{T}\left\|\delta_{t}-\theta_{t}\right\|^{2} d t\right]
$$

where $E_{\theta}$ is the expectation with respect to a probability $P_{\theta}$.
Let $X=\left(X^{1}, \ldots, X^{d}\right)$ be a normal vector with mean $\theta=\left(\theta^{1}, \ldots, \theta^{d}\right) \in \mathbb{R}^{d}$ and identity covariance matrix $\sigma^{2} I_{d}$. The usual maximum likelihood estimator of $\theta$ is $X$ itself. Moreover, it is efficient in the sense that the Cramer-Rao bound over all unbiased estimators is attained by $X$. That is

$$
\sigma^{2} d=E\left[\|X-\theta\|_{d}^{2}\right]=\inf _{\xi \in \mathcal{S}} E\left[\|\xi-\theta\|_{d}^{2}\right],
$$

where $\mathcal{S}$ is the class of unbiased estimators of $\theta$ and $\|.\|_{d}$ denotes the Euclidean norm on $\mathbb{R}^{d}$.
[12] constructed biased superefficient estimators of $\theta$ of the form

$$
\delta_{a, b}(X)=\left(1-\frac{b}{a+\|X\|^{2}}\right) X
$$

for $a$ sufficiently small and $b$ sufficiently large when $d \geq 3$. 4 sharpened later this result and presented an explicit class of biased superefficient estimators of the form

$$
\left(1-\frac{a}{\|X\|_{d}^{2}}\right) X, \text { for } 0<a<2(d-2)
$$

Recently, an infinite-dimensional extension of this result has been given by [10]. The authors constructed unbiased estimators of the drift $\left(\theta_{t}\right)_{t \in[0, T]}$ of a continuous Gaussian martingale $\left(X_{t}\right)_{t \in[0, T]}$ with quadratic variation $\sigma_{t}^{2} d t$, where $\sigma \in$ $L^{2}([0, T], d t)$ is an a.e. non-vanishing function. More precisely, they proved that $\hat{\theta}=\left(X_{t}\right)_{t \in[0, T]}$ is an efficient estimator of $\left(\theta_{t}\right)_{t \in[0, T]}$. On the other hand, using Malliavin calculus, they constructed superefficient estimators for the drift of a Gaussian processe of the form:

$$
X_{t}:=\int_{0}^{t} K(t, s) d W_{s}, \quad t \in[0, T],
$$

where $\left(W_{t}\right)_{t \in[0, T]}$ is a standard Brownian motion and $K(.,$.$) is a deterministic kernel.$ These estimators are biased and of the form $X_{t}+D_{t} \log F$, where $F$ is a positive superharmonic random variable and $D$ is the Malliavin derivative.

In Section 3, we prove, using technic based on the fractional calculus and Girsanov theorem, that $\widehat{\theta}=B^{H}$ is an efficient estimator of $\theta$ under the probability $P_{\theta}$ with risk

$$
\mathcal{R}\left(\theta, B^{H}\right)=E_{\theta}\left[\int_{0}^{T}\left\|B_{t}^{H}-\theta_{t}\right\|^{2} d t\right]=\frac{T^{2 H+1}}{2 H+1} d .
$$

Moreover, we will establish that $\hat{\theta}=B^{H}$ is a maximum likelihood estimator of $\theta$.
In Section 4, we construct a class of biased estimators of James-Stein type of the form

$$
\delta\left(B^{H}\right)_{t}=\left(1-a t^{2 H}\left(\frac{r\left(\left\|B_{t}^{H}\right\|^{2}\right)}{\left\|B_{t}^{H}\right\|^{2}}\right)\right) B_{t}^{H}, \quad t \in[0, T]
$$

We give sufficient conditions on the function $r$ and on the constant $a$ in order that $\delta\left(B^{H}\right)$ dominates $B^{H}$ under the usual quadratic risk i.e.

$$
\begin{equation*}
\mathcal{R}\left(\theta, \delta\left(B^{H}\right)\right)<\mathcal{R}\left(\theta, B^{H}\right) \quad \text { for all } \theta \in M \tag{1.2}
\end{equation*}
$$

## 2 Preliminaries

This section contains the elements from fractional calculus that we will need in the paper.

The fractional Brownian motion $B^{H}$ has the following stochastic integral representation (see for instance, []], [8])

$$
\begin{equation*}
B_{t}^{H, i}=\int_{0}^{t} K_{H}(t, s) d W_{s}^{i}, \quad i=1, \ldots, d ; \quad t \in[0, T] \tag{2.3}
\end{equation*}
$$

where $W=\left(W^{1}, \ldots, W^{d}\right)$ denotes the d-dimensional Brownian motion and the kernel $K_{H}(t, s)$ is equal to

$$
\begin{aligned}
c_{H}(t-s)^{H-\frac{1}{2}}+c_{H}\left(\frac{1}{2}-H\right) \int_{s}^{t}(u-s)^{H-\frac{3}{2}}\left(1-\left(\frac{s}{u}\right)^{\frac{1}{2}-H}\right) d u & \text { if } H \leq \frac{1}{2} \\
c_{H}\left(H-\frac{1}{2}\right) \int_{s}^{t}(u-s)^{H-\frac{3}{2}}\left(\frac{s}{u}\right)^{H-\frac{1}{2}} d u & \text { if } H>\frac{1}{2}
\end{aligned}
$$

if $s<t$ and $K_{H}(t, s)=0$ if $s \geq t$. Here $c_{H}$ is the normalizing constant

$$
c_{H}=\sqrt{\frac{2 H \Gamma\left(\frac{3}{2}-H\right)}{\Gamma\left(H+\frac{1}{2}\right) \Gamma(2-2 H)}}
$$

where $\Gamma$ is the Euler function.
We recall some basic definitions and results on classical fractional calculus which we will need. General information about fractional calculus can be found in [11].
The left fractional Riemann-Liouville integral of $f \in L^{1}((a, b))$ of order $\alpha>0$ on $(a, b)$ is given at almost all $x \in(a, b)$ by

$$
I_{a^{+}}^{\alpha} f(x)=\frac{1}{\Gamma(\alpha)} \int_{a}^{x}(x-y)^{\alpha-1} f(y) d y .
$$

If $f \in I_{a^{+}}^{\alpha}\left(L^{p}(a, b)\right)$ with $0<\alpha<1$ and $p>1$ then the left-sided Riemann-Liouville derivative of $f$ of order $\alpha$ defined by

$$
D_{a^{+}}^{\alpha} f(x)=\frac{1}{\Gamma(1-\alpha)}\left(\frac{f(x)}{(x-a)^{\alpha}}+\alpha \int_{a}^{x} \frac{f(x)-f(y)}{(x-y)^{\alpha+1}} d y\right)
$$

for almost all $x \in(a, b)$.
For $H \in(0,1)$, the integral transform

$$
\left(K_{H} f\right)(t)=\int_{0}^{t} K_{H}(t, s) f(s) d s
$$

is a isomorphism from $L^{2}([0,1])$ onto $I_{0^{+}}^{H+\frac{1}{2}}\left(L^{2}([0,1])\right)$ and its inverse operator $K_{H}^{-1}$ is given by

$$
\begin{align*}
& K_{H}^{-1} f=t^{H-\frac{1}{2}} D_{0^{+}}^{H-\frac{1}{2}} t^{\frac{1}{2}-H} f^{\prime} \quad \text { for } H>1 / 2  \tag{2.4}\\
& K_{H}^{-1} f=t^{\frac{1}{2}-H} D_{0^{+}}^{\frac{1}{2}-H} t^{H-\frac{1}{2}} D_{0^{+}}^{2 H} f \quad \text { for } H<1 / 2 \tag{2.5}
\end{align*}
$$

Moreover, for $H<\frac{1}{2}$, if $f$ is an absolutely continuous function then $K_{H}^{-1} f$ can be represented of the form (see [9])

$$
\begin{equation*}
K_{H}^{-1} f=t^{H-\frac{1}{2}} I_{0^{+}}^{\frac{1}{2}-H} t^{\frac{1}{2}-H} f^{\prime} . \tag{2.6}
\end{equation*}
$$

## 3 The maximum likelihood estimator and Cramer-Rao type bound

We consider a function $\theta=\left(\theta^{1}, \ldots, \theta^{d}\right)$ belonging to $M$. An estimator $\xi=\left(\xi^{1}, \ldots, \xi^{d}\right)$ of $\theta=\left(\theta^{1}, \ldots, \theta^{d}\right)$ is called unbiased if, for every $t \in[0, T]$

$$
E_{\theta}\left(\xi_{t}^{i}\right)=\theta_{t}^{i}, \quad i=1, \ldots, d
$$

and it is called adapted if, for each $i=1, \ldots, d, \xi^{i}$ is adapted to $\left(\mathcal{F}_{t}^{i}\right)_{t \in[0, T]}$. Since for any $i=1, \ldots, d$, the function $\theta^{i}$ is deterministic and

$$
\int_{0}^{T}\left(K_{H}^{-1}\left(\theta^{i}\right)(s)\right)^{2} d s<\infty
$$

then Girsanov theorem yields that there exists a probability measure $P_{\theta}$ absolutely continuous with respect to $P$ under which the process $\widetilde{B}^{H}:=\left(\widetilde{B}_{t}^{H} ; t \in[0, T]\right)$ defined by

$$
\begin{equation*}
\widetilde{B}_{t}^{H}=B_{t}^{H}-\theta_{t}, \quad t \in[0, T] \tag{3.7}
\end{equation*}
$$

is a d-dimensional fBm with Hurst parameter $H$ and mean zero. Moreover the Girsanov density of $P_{\theta}$ with respect to $P$ is given by:

$$
\frac{d P_{\theta}}{d P}=\exp \left[\sum_{i=1}^{d}\left(\int_{0}^{T} K_{H}^{-1}\left(\theta^{i}\right)(s) d W_{s}^{i}-\frac{1}{2} \int_{0}^{T}\left(K_{H}^{-1}\left(\theta^{i}\right)(s)\right)^{2} d s\right)\right]
$$

and

$$
\widetilde{B}_{t}^{H}=\int_{0}^{t} K_{H}(t, s) d \widetilde{W}_{s}
$$

where $\widetilde{W}$ is a d-dimensional Brownian motion under the probability $P_{\theta}$ and

$$
\widetilde{W}_{t}^{i}=W_{t}^{i}-\int_{0}^{t} K_{H}^{-1}\left(\theta^{i}\right)(s) d s, \quad i=1, \ldots, d ; \quad t \in[0, T]
$$

The equation (3.7) implies that $B^{H}$ is an unbiased and adapted estimator of $\theta$ under probability $P_{\theta}$. In addition, we obtain the Cramer-Rao type bound:

$$
R(H, \hat{\theta}):=\mathcal{R}\left(\theta, B^{H}\right)=\int_{0}^{T} E_{\theta}\left\|\widetilde{B}_{t}^{H}\right\|^{2} d t=d \int_{0}^{T} t^{2 H} d t=\frac{T^{2 H+1}}{2 H+1} d
$$

The first main result of this section is given by the following proposition which asserts that $\widehat{\theta}=B^{H}$ is an efficient estimator of $\theta$.

Theorem 1 Assume that $H<\frac{1}{2}$. If $\xi$ is an unbiased and adapted estimator of $\theta$, then

$$
\begin{equation*}
E_{\theta} \int_{0}^{T}\left\|\xi_{t}-\theta_{t}\right\|^{2} d t \geq R(H, \hat{\theta}) \tag{3.8}
\end{equation*}
$$

Proof: Since $\xi$ is unbiased, then for every $\varphi \in M$ we have

$$
E_{\varphi}\left(\xi_{t}^{j}\right)=E_{\varphi}\left(\varphi_{t}^{j}\right), \quad j=1, \ldots, d
$$

Let $\varphi=\theta+\varepsilon \psi$ with $\psi \in M$ and $\varepsilon \in \mathbb{R}$. Then for every $t \in[0, T]$ and $j \in\{1, \ldots, d\}$, we have

$$
\begin{aligned}
E_{\theta+\varepsilon \psi}\left(\xi_{t}^{j}\right) & =E_{\theta+\varepsilon \psi}\left(\theta_{t}^{j}+\varepsilon \psi_{t}^{j}\right) \\
& =E_{\theta+\varepsilon \psi}\left(\theta_{t}^{j}\right)+\varepsilon \psi_{t}^{j}
\end{aligned}
$$

This implies that for every $j=1, \ldots, d$

$$
\begin{aligned}
\psi_{t}^{j}= & \frac{d}{d \varepsilon / \varepsilon=0} E_{\theta+\varepsilon \psi}\left(\xi_{t}^{j}-\theta_{t}^{j}\right) \\
= & E\left(\frac { d } { d \varepsilon } { } _ { / \varepsilon = 0 } \operatorname { e x p } \left[\sum _ { i = 1 } ^ { d } \left(\int_{0}^{t} K_{H}^{-1}\left(\theta^{i}+\varepsilon \psi^{i}\right)(s) d W_{s}^{i}\right.\right.\right. \\
& \left.\left.\left.\left.-\frac{1}{2} \int_{0}^{t}\left(K_{H}^{-1}\left(\theta^{i}+\varepsilon \psi^{i}\right)(s)\right)^{2}\right) d s\right)\right]\left(\xi_{t}^{j}-\theta_{t}^{j}\right)\right) \\
= & E_{\theta}\left(\sum_{i=1}^{d}\left[\int_{0}^{t} K_{H}^{-1}\left(\psi^{i}\right)(s) d W_{s}^{i}-\int_{0}^{t} K_{H}^{-1}\left(\psi^{i}\right)(s) K_{H}^{-1}\left(\theta^{i}\right)(s) d s\right]\right. \\
= & E_{\theta}\left(\sum_{i=1}^{d}\left[\int_{0}^{t} K_{H}^{-1}\left(\psi^{i}\right)(s) d \widetilde{W}_{s}^{i}\right]\left(\xi_{t}^{j}-\theta_{t}^{j}\right)\right) \\
= & E_{\theta}\left(\left[\int_{0}^{t} K_{H}^{-1}\left(\psi^{j}\right)(s) d \widetilde{W}_{s}^{j}\right]\left(\xi_{t}^{j}-\theta_{t}^{j}\right)\right) .
\end{aligned}
$$

Applying Cauchy-Schwarz inequality in $L^{2}\left(\Omega, d P_{\theta}\right)$, we obtain that for every $t \in[0, T]$

$$
\begin{aligned}
\left\|\psi_{t}\right\|^{2}=\sum_{j=1}^{d}\left(\psi_{t}^{j}\right)^{2} \leq & \sum_{j=1}^{d} E_{\theta}\left(\left(\xi_{t}^{j}-\theta_{t}^{j}\right)^{2}\right) E_{\theta}\left(\left[\int_{0}^{t} K_{H}^{-1}\left(\psi^{j}\right)(s) d \widetilde{W}_{s}^{j}\right]^{2}\right) \\
& =\sum_{j=1}^{d} E_{\theta}\left[\left(\left(\xi_{t}^{j}-\theta_{t}^{j}\right)^{2}\right) \int_{0}^{t}\left(K_{H}^{-1}\left(\psi^{j}\right)(s)\right)^{2} d s\right]
\end{aligned}
$$

We take for each $j=1, \ldots, d, \psi_{t}^{j}=t^{2 H}$. Since $t \longrightarrow t^{2 H}$ is absolutely continuous function, then by (2.6), a simple calculation shows that

$$
\begin{aligned}
K_{H}^{-1}\left(t^{2 H}\right) & =2 H t^{H-\frac{1}{2}} I_{0^{+}}^{\frac{1}{2}-H} t^{H-\frac{1}{2}} \\
& =\frac{2 H \beta\left(\frac{1}{2}-H, H+\frac{1}{2}\right)}{\Gamma\left(\frac{1}{2}-H\right)} t^{H-1 / 2} \\
& =2 H\left(\Gamma\left(\frac{1}{2}+H\right)\right) t^{H-1 / 2} .
\end{aligned}
$$

It is known that

$$
\begin{equation*}
0 \leq \Gamma(z) \leq 1 \quad \text { for every } z \in[1,2] . \tag{3.9}
\end{equation*}
$$

Combining the facts that $z \Gamma(z)=\Gamma(z+1), z>0,2 H \leq\left(H+\frac{1}{2}\right)^{2}$ and (3.9), we obtain

$$
d t^{2 H}=\left\|\psi_{t}\right\|^{2} \leq\left(\Gamma\left(\frac{3}{2}+H\right)\right)^{2} E_{\theta}\left(\left\|\xi_{t}-\theta_{t}\right\|^{2}\right) \leq E_{\theta}\left(\left\|\xi_{t}-\theta_{t}\right\|^{2}\right)
$$

Hence, by an integration with respect to $d t$, we get

$$
R(H, \hat{\theta})=\frac{T^{2 H+1}}{2 H+1} \leq E_{\theta} \int_{0}^{T}\left\|\xi_{t}-\theta_{t}\right\|^{2} d t
$$

Therefore (3.8) is satisfied.
Corollary 1 The process $\hat{\theta}=B^{H}$ is a maximum likelihood estimator of $\theta$.

Proof: We have for every $\psi \in M$

$$
\left.\frac{d}{d \varepsilon} / \varepsilon=0 \text { exp }\left[\sum_{i=1}^{d} \int_{0}^{t} K_{H}^{-1}\left(\hat{\theta}^{i}+\varepsilon \psi^{i}\right)(s) d W_{s}^{i}-\frac{1}{2} \int_{0}^{t}\left(K_{H}^{-1}\left(\hat{\theta}^{i}+\varepsilon \psi^{i}\right)(s)\right)^{2}\right) d s\right]=0
$$

Hence

$$
\sum_{i=1}^{d}\left(\int_{0}^{t} K_{H}^{-1}\left(\psi^{i}\right)(s) d W_{s}^{i}-\int_{0}^{t} K_{H}^{-1}\left(\psi^{i}\right)(s) K_{H}^{-1}\left(\hat{\theta^{i}}\right)(s) d s\right)=0
$$

Which implies that for every $i=1, \ldots, d$

$$
E\left(\int_{0}^{t} K_{H}^{-1}\left(\psi^{i}\right)(s) d W_{s}^{i}-\int_{0}^{t} K_{H}^{-1}\left(\psi^{i}\right)(s) K_{H}^{-1}\left(\hat{\theta^{i}}\right)(s) d s\right)^{2}=0
$$

Then, for each $i=1, \ldots, d$

$$
W_{t}^{i}=\int_{0}^{t} K_{H}^{-1}\left(\hat{\theta}^{i}\right)(s) d s, \quad t \in[0, T]
$$

Therefore by (2.3), we obtain that $B^{H}=\hat{\theta}$.

## 4 Superefficient James-Stein type estimators

The aim of this section is to construct superefficient estimators of $\theta$ which dominate, under the usual quadratic risk, the natural MLE estimator $B^{H}$. The class of estimators considered here are of the form

$$
\begin{equation*}
\delta\left(B^{H}\right)_{t}=B_{t}^{H}+g\left(B_{t}^{H}, t\right), \quad t \in[0, T] \tag{4.10}
\end{equation*}
$$

where $g: \mathbb{R}^{d+1} \longrightarrow \mathbb{R}^{d}$ is a function. The problem turns to find sufficient conditions on $g$ such that $\mathcal{R}\left(\theta, \delta\left(B^{H}\right)\right)<\infty$ and the risk difference is negative, i.e.

$$
\Delta \mathcal{R}(\theta)=\mathcal{R}\left(\theta, \delta\left(B^{H}\right)\right)-\mathcal{R}\left(\theta, B^{H}\right)<0 .
$$

In the sequel we assume that the function $g$ satisfies the following assumption:

$$
\text { (A) }\left\{\begin{array}{l}
E_{\theta}\left[\int_{0}^{T}\left\|g\left(B_{t}^{H}, t\right)\right\|_{d}^{2} d t\right]<\infty, \\
\text { the partial derivatives } \partial_{i} g^{i}:=\frac{\partial g^{i}}{\partial x^{i}}, i=1, \ldots, n \text { of } g \text { exist. }
\end{array}\right.
$$

Then $\mathcal{R}\left(\theta, \delta\left(B^{H}\right)\right)<\infty$. Moreover

$$
\begin{aligned}
\Delta \mathcal{R}(\theta) & =E_{\theta}\left[\int_{0}^{T}\left\|B_{t}^{H}+g\left(B_{t}^{H}, t\right)-\theta_{t}\right\|_{d}^{2}-\left\|B_{t}^{H}-\theta_{t}\right\|_{d}^{2} d t\right] \\
& =E_{\theta}\left[\int_{0}^{T}\left\|g\left(B_{t}^{H}, t\right)\right\|_{d}^{2}+2 \sum_{i=1}^{d}\left(g^{i}\left(B_{t}^{H}, t\right)\left(B_{t}^{H, i}-\theta_{t}^{i}\right)\right) d t\right] .
\end{aligned}
$$

In addition,

$$
\begin{aligned}
& \quad E_{\theta} \int_{0}^{T} \sum_{i=1}^{d}\left(g^{i}\left(B_{t}^{H}, t\right)\left(B_{t}^{H, i}-\theta_{t}^{i}\right)\right) d t \\
& =\sum_{i=1}^{d} \int_{0}^{T}\left(2 \pi t^{2 H}\right)^{-\frac{d}{2}}\left(\int_{\mathbb{R}^{d}} g^{i}\left(x^{1}, \ldots, x^{d}, t\right)\left(x^{i}-\theta_{t}^{i}\right)\right. \\
& \left.\times e^{-\frac{\sum_{j=1}^{d}\left(x^{j}-\theta_{t}^{j}\right) 2}{2 t^{2 H}}} d x^{1} \ldots d x^{d}\right) d t \\
& =\sum_{i=1}^{d} \int_{0}^{T}\left(2 \pi t^{2 H}\right)^{-\frac{d}{2}}\left(\int_{\mathbb{R}^{d}} t^{2 H} \partial_{i} g^{i}\left(x^{1}, \ldots, x^{d}, t\right)\right. \\
& \left.\quad \times e^{-\frac{\sum_{j=1}^{d}\left(x^{j}-\theta_{t}^{j}\right) 2}{2 t^{2 H}}} d x^{1} \ldots d x^{d}\right) d t \\
& = \\
& \sum_{i=1}^{d} \int_{0}^{T}\left(t^{2 H} E_{\theta} \partial_{i} g^{i}\left(B_{t}^{H}, t\right)\right) d t=E_{\theta}\left[\sum_{i=1}^{d} \int_{0}^{T} t^{2 H} \partial_{i} g^{i}\left(B_{t}^{H}, t\right) d t\right] .
\end{aligned}
$$

Consequently, the risk difference equals

$$
\begin{equation*}
\Delta \mathcal{R}(\theta)=E_{\theta}\left[\int_{0}^{T}\left(\left\|g\left(B_{t}^{H}, t\right)\right\|^{2}+2 t^{2 H} \sum_{i=1}^{d} \partial_{i} g^{i}\left(B_{t}^{H}, t\right)\right) d t\right] . \tag{4.11}
\end{equation*}
$$

We can now state the following theorem.
Theorem 2 Let $g: \mathbb{R}^{d+1} \longrightarrow \mathbb{R}^{d}$ be a function satisfying (A). A sufficient conditions for the estimator $\left(B_{t}^{H}+g\left(B_{t}^{H}, t\right)\right)_{t \in[0, T]}$ to dominate $B^{H}$ under the usual quadratic risk is

$$
E_{\theta}\left[\int_{0}^{T}\left(\left\|g\left(B_{t}^{H}, t\right)\right\|^{2}+2 t^{2 H} \sum_{i=1}^{d} \partial_{i} g^{i}\left(B_{t}^{H}, t\right)\right) d t\right]<0
$$

As an application, take $g$ of the form

$$
\begin{equation*}
g(x, t)=a t^{2 H} \frac{r\left(\|x\|^{2}\right)}{\|x\|^{2}} x \tag{4.12}
\end{equation*}
$$

where $a$ is a constant strictly positive and $r: \mathbb{R}^{+} \rightarrow \mathbb{R}^{+}$is bounded derivable function. The next lemma give a sufficient condition for $g$ in (4.12) to satisfies the assumption (A).

Lemma 1 If $d \geq 3$ and $H<\frac{1}{2}$ then

$$
\begin{equation*}
E\left[\int_{0}^{T} \frac{1}{\left\|B_{t}^{H}\right\|^{2}} d t\right]<\infty \tag{4.13}
\end{equation*}
$$

Proof: Firstly the integral given by (4.13) is well defined, because

$$
(d t \times P)\left((t, w) ; B_{t}^{H}(w)=0\right)=0
$$

where $(d t \times P)$ is the product measure.
Using the change of variable and $d \geq 3$ we see that

$$
E \int_{0}^{T} \frac{1}{\left\|B_{t}^{H}\right\|^{2}} d t=\int_{0}^{T} \frac{d t}{t^{2 H}} \int_{\mathbb{R}^{d}} \frac{e^{-\frac{\|y\|^{2}}{2}}}{\sqrt{2 \pi}\|y\|^{2}} d y \leq C \int_{0}^{T} \frac{1}{t^{2 H}} d t
$$

where $C$ is a constant depending only on $d$. Furthermore, since $H<\frac{1}{2}$ then (4.13) holds.

Theorem 3 Assume that $d \geq 3$. If the function $r$, the constant $a$ and the parameter $H$ satisfy:
i) $0 \leq r() \leq$.
ii) $r(\cdot)$ is differentiable and increasing
iii) $0<a \leq 2(d-2)$ and $H<1 / 2$,
then the estimator

$$
\delta\left(B^{H}\right)=B_{t}^{H}-a t^{2 H} \frac{r\left(\left\|B_{t}^{H}\right\|^{2}\right)}{\left\|B_{t}^{H}\right\|^{2}} B_{t}^{H}, \quad t \in[0, T]
$$

dominates $B^{H}$.

Proof: It suffices to prove that $\Delta \mathcal{R}(\theta)<0$. From (4.11) and the hypothesis $i$ ) and ii) we can write

$$
\begin{aligned}
\Delta \mathcal{R}(\theta)= & a E_{\theta}\left[\int _ { 0 } ^ { T } t ^ { 4 H } \left(\frac{a r^{2}\left(\left\|B_{t}^{H}\right\|^{2}\right)}{\left\|B_{t}^{H}\right\|^{2}}-2(d-2) \frac{r\left(\left\|B_{t}^{H}\right\|^{2}\right)}{\left\|B_{t}^{H}\right\|^{2}}\right.\right. \\
& \left.\left.-4 r^{\prime}\left(\left\|B_{t}^{H}\right\|^{2}\right)\right) d t\right] \\
\leq & a[a-2(d-2)] E_{\theta}\left[a \int_{0}^{T} t^{4 H} \frac{r\left(\left\|B_{t}^{H}\right\|^{2}\right)}{\left\|B_{t}^{H}\right\|^{2}}\right]
\end{aligned}
$$

Combining this fact with the assumption $i i i$ ) yields that the risk difference is negative. Which proves the desired result.
For $r=1$, we obtain a James-Stein type estimator:
Corollary 2 Let $d \geq 3,0<H<\frac{1}{2}$ and $0<a \leq 2(d-2)$. Then the estimator

$$
\left(1-\frac{a t^{2 H}}{\left\|B_{t}^{H}\right\|^{2}}\right) B_{t}^{H}, \quad t \in[0, T]
$$

dominates $B^{H}$.

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